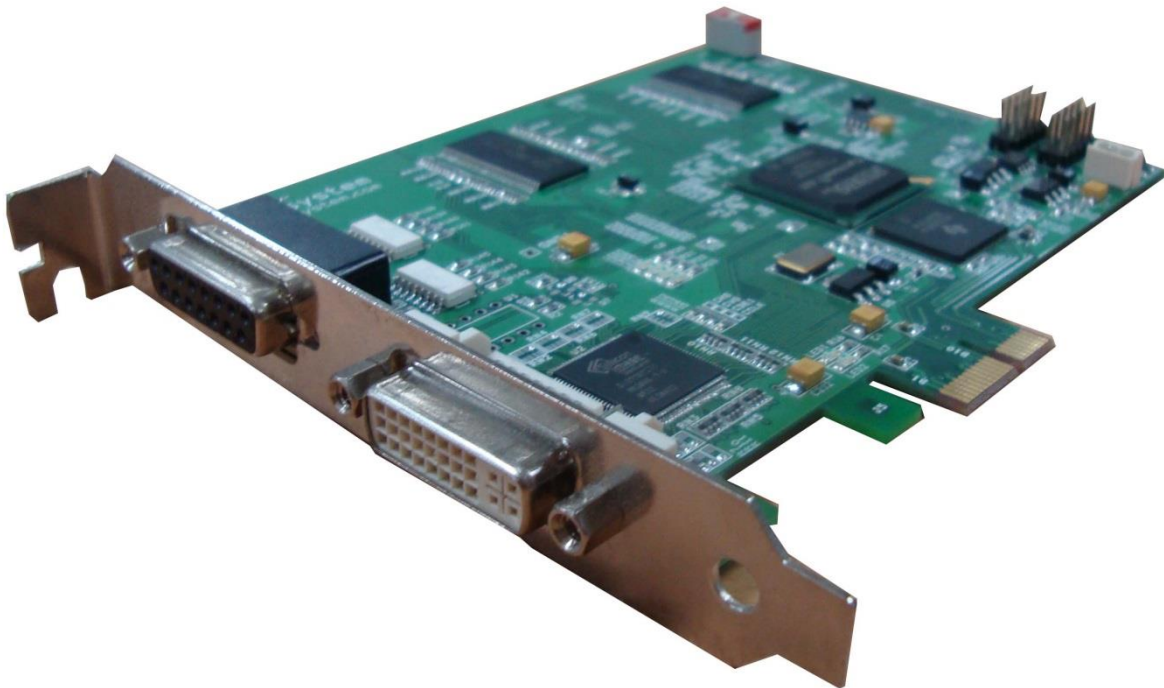


# PCIe-FRM14

## API Manual

Version 1.2



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## Board Level API Functions

### Overview

int	OpenDAQDevice (void)
BOOL	ResetBoard (int nBoard)
BOOL	CloseDAQDevice (void)
int	GetBoardNum (void)

### OpenDAQDevice

This function initializes the device. You may call this function at the very first time you run the program.

**BOOL**      **OpenDAQDevice (void)**

**Parameters:** None .

**Return Value:**

If the function succeeds, it returns the number of boards which were detected.

If the function fails, the return value is -1, it means there is no device in the system.

(In case of multi-board, up to 4 is possible)

### ResetBoard

This function initializes a device at currently equipped system (PC).

**BOOL**      **ResetBoard (int nBoard)**

**Parameters:**

nBoard : Numbers of discovered device. The board number is set up by DIP switch.

**Return Value:**

It returns TRUE in case of the success of reset and initialization.

If you get FALSE you should not call any API functions with the board and call the

**CloseDAQDevice()** instead.

## CloseDAQDevice

This function closes all opened devices (boards). If using of device is finished, you must certainly close a device for making it other programs so as usable.

**BOOL**           **CloseDAQDevice (void)**

**Parameters:** None.

**Return Value:**

If the function fail to close, it returns "FALSE".

If the function succeed to close, it returns "TRUE".

## GetBoardNum

This function returns currently detected board number in the system. If one board is installed, "1" is displayed. Up to 4 can be connected, and "4" is the maximum value.

**int**               **GetBoardNum (void)**

**Parameters:** None

**Return Value:**

The number of boards, The Board number is set by dip switch.

## LVDS(Camera Link) API Functions

### Overview

BOOL	LVDS_Init (void)
BOOL	LVDS_Start (void)
BOOL	LVDS_GetFrame (DWORD* nCnt, unsigned char* buf)
BOOL	LVDS_Close (void)
BOOL	LVDS_SetResolution (DWORD xRes, DWORD yRes)
BOOL	LVDS_GetResolution (DWORD *xRes, DWORD *yRes)
BOOL	LVDS_Stop (void)
BOOL	LVDS_SetDataMode (int nMode)
BOOL	LVDS_GetVersion (int *nVersion)

### LVDS\_Init

This function initializes resources used for the LVDS sub-system, for example interrupt and LVDS control register.

#### BOOL LVDS\_Init (void)

**Parameters:** None.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

### LVDS\_Start

This function starts receiving frame data. After calling this function, you can check whether the data is complete by calling the LVDS\_GetFrame function.

#### BOOL LVDS\_Start (void)

**Parameters:** None.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## LVDS\_GetFrame

This function starts receiving frame data. After calling this function, you can check whether the data is complete by calling the LVDS\_GetFrame function.

**BOOL**            **LVDS\_GetFrame (DWORD\* nCnt, unsigned char\* buf)**

**Parameters:**

nCnt : It is the address which contains the number of data to be received in byte size. Specifies the size buffer when the function is called, and read the values of the variables after a call to find out how many actually read. The data size is in bytes.

buf : Frame buffer pointer.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, check the values of the size that you want to read nCnt.

**(Note)** If the frame data is not completed, FALSE is returned immediately and the return occurs with the nCnt value set to 0.

## LVDS\_Close

This function releases all resource were used for LVDS function. The application program calls this function when the program ends.

**BOOL**            **LVDS\_Close (void)**

**Parameters:** None.

**Return Value :**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## LVDS\_SetResolution

This function selects the resolution of the Video input. Frame size is determined according to this resolution.

**BOOL**            **LVDS\_SetResolution (DWORD xRes, DWORD yRes)**

**Parameters:**

xRes : Value of the horizontal Camera resolution

yRes : Value of the vertical Camera resolution

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## LVDS\_GetResolution

This function gets currently configured camera's frame resolution

**BOOL**            **LVDS\_GetResolution (DWORD \*xRes, DWORD \*yRes)**

**Parameters:**

\*xRes : Address pointer to receive horizontal Camera resolution

\*yRes : Address pointer to receive vertical Camera resolution

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## LVDS\_Stop

This function stops the frame data capture.

**BOOL**            **LVDS\_Stop (void)**

**Parameters:** None.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".



## LVDS\_SetDataMode

This function sets image pixel data mode.

### **BOOL          LVDS\_SetDataMode (int nMode)**

**Parameters:**

nMode : If it is "2", it is 24bit Mode, and if it is "Others", it is 16bit Mode.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## LVDS\_GetVersion

This function gets FPGA version.

### **BOOL          LVDS\_GetVersion (int \*nVersion)**

**Parameters:**

nVersion : The pointer of the FPGA version.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## DIO(Digital Input Output) API Functions

### Overview

BOOL            DIO\_Read (void)  
BOOL            DIO\_Write (DWORD val)

### DIO\_Read

This function reads the Digital Input state.

BOOL            DIO\_Read (void)

**Parameters:** None.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

### DIO\_Write

This function sets up the Digital Output pin state.

BOOL            DIO\_Write (DWORD val)

**Parameters:**

val : The value to be written to the port.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## Multi Board support APIs

In case of single board API, only one board is used in the installed system. However, in a system with two or more boards installed (up to 4 supported), multiple APIs must be used. Multi board API is only available for FPGA version #2 or higher boards.

### Multi Board LVDS(Camera Link) APIs

#### *Overview*

BOOL	LVDS_Init_Mul (int nBoard)
BOOL	LVDS_Start_Mul (int nBoard)
BOOL	LVDS_GetFrame_Mul (int nBoard, DWORD* nCnt, unsigned char* buf)
BOOL	LVDS_Close_Mul (int nBoard)
BOOL	LVDS_SetResolution_Mul (int nBoard, DWORD xRes, DWORD yRes)
BOOL	LVDS_GetResolution_Mul (int nBoard, DWORD *xRes, DWORD *yRes)
BOOL	LVDS_Stop_Mul (int nBoard)
BOOL	LVDS_SetDataMode_Mul (int nBoard, int nMode)
BOOL	LVDS_GetVersion_Mul (int nBoard, int *nVersion)

#### LVDS\_Init\_Mul

This function initializes resources used for the LVDS sub-system, for example interrupt and LVDS control register.

**BOOL** LVDS\_Init\_Mul (int nBoard)

**Parameters:**

nBoard : It informs a board number at currently equipped system.

The board number set up by DIP switch.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## LVDS\_Start\_Mul

This function starts receiving frame data. After calling this function, you can check whether the data is complete by calling the LVDS\_GetFrame function.

### **BOOL** LVDS\_Start\_Mul (int nBoard)

#### **Parameters:**

nBoard : It informs a board number at currently equipped system.  
The board number set up by DIP switch.

#### **Return Value:**

If the function call fails, it returns "FALSE".  
If the function call succeeds, it returns "TRUE".

## LVDS\_GetFrame\_Mul

This function checks whether the frame data is complete, and if it is, retrieves the frame data. At this time, the size of the buffer to receive data must be informed.

### **BOOL** LVDS\_GetFrame\_Mul (int nBoard, DWORD\* nCnt, unsigned char\* buf)

#### **Parameters:**

nBoard : It informs a board number at currently equipped system.  
The board number set up by DIP switch.  
nCnt : It is the address which contains the number of data to be received in byte size. Specifies the size buffer when the function is called, and read the values of the variables after a call to find out how many actually read. The data size is in bytes.  
buf : The buffer address.

#### **Return Value:**

If the function call fails, it returns "FALSE".  
If the function call succeeds, it returns "TRUE".

## LVDS\_Close\_Mul

This function releases all resource were used for LVDS function. The application program calls this function when the program ends.

### **BOOL           LVDS\_Close\_Mul (int nBoard)**

#### **Parameters:**

nBoard : It informs a board number at currently equipped system.  
The board number set up by DIP switch.

#### **Return Value :**

If the function call fails, it returns "FALSE".  
If the function call succeeds, it returns "TRUE".

## LVDS\_SetResolution\_Mul

This function selects the resolution of the Video input. Frame size is determined according to this resolution.

### **BOOL           LVDS\_SetResolutuion\_Mul (int nBoard, DWORD xRes, DWORD yRes)**

#### **Parameters:**

nBoard : It informs a board number at currently equipped system.  
The board number set up by DIP switch.

xRes : Value of the horizontal Camera resolution

yRes : Value of the vertical Camera resolution

#### **Return Value:**

If the function call fails, it returns "FALSE".  
If the function call succeeds, it returns "TRUE".

## LVDS\_GetResolution\_Mul

This function gets currently configured camera's frame resolution

**BOOL**            **LVDS\_GetResolution\_Mul (int nBoard, DWORD \*xRes, DWORD \*yRes)**

**Parameters:**

nBoard : It informs a board number at currently equipped system.

The board number set up by DIP switch.

xRes : Address pointer to receive horizontal Camera resolution

yRes : Address pointer to receive vertical Camera resolution

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## LVDS\_Stop\_Mul

This function stops the frame data capture.

**BOOL**            **LVDS\_Stop\_Mul (int nBoard)**

**Parameters:**

nBoard : It informs a board number at currently equipped system.

The board number set up by DIP switch.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## LVDS\_SetDataMode\_Mul

This function sets image pixel data mode.

**BOOL**            **LVDS\_SetDataMode\_Mul (int nBoard, int nMode)**

**Parameters:**

nBoard : It informs a board number at currently equipped system.

The board number set up by DIP switch.

nMode : If it is "2", it is 24bit Mode, and if it is "Others", it is 16bit Mode.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## LVDS\_GetVersion\_Mul

This function gets a FPGA version.

**BOOL** LVDS\_GetVersion\_Mul (int nBoard, int \*nVersion)

**Parameters:**

nBoard : It informs a board number at currently equipped system.

The board number set up by DIP switch.

\*nVersion : The pointer of the FPGA version.

**Return Value:**

If the function call fails, it returns "FALSE".

If the function call succeeds, it returns "TRUE".

## Multi-board DIO(Digital Input Output) API Functions

### *Overview*

**BOOL**            **DIO\_Read\_Mul (int nBoard)**

**BOOL**            **DIO\_Write\_Mul (int nBoard, DWORD val)**

### **DIO\_Read\_Mul**

This function reads from input port.

**DWORD**            **DIO\_Read\_Mul (int nBoard)**

#### **Parameters:**

nBoard : It informs a board number at currently equipped system.  
The board number set up by DIP switch.

#### **Return Value:**

If the function call fails, it returns "FALSE".  
If the function call succeeds, it returns "TRUE".

### **DIO\_Write\_Mul**

This function writes to output port.

**BOOL**            **DIO\_Write\_Mul (int nBoard, DWORD val)**

#### **Parameters:**

nBoard : It informs a board number at currently equipped system.  
The board number set up by DIP switch.  
val : The value to be written to the port.

#### **Return Value:**

If the function call fails, it returns "FALSE".  
If the function call succeeds, it returns "TRUE".



# Memo

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